

Com S 477/577 Problem Solving Techniques for Applied Computer Science

Exam 1

2:10-3:25am

Thursday, Oct 16, 2008

Name: _____

ID (4-digit): ____ _

1	2	3	4	5	Total
44	14	16	12	14	100

1. [44 pts] *Short Questions*

(a) [12 pts] Determine if the following statements are true or false. For each statement, mark only the answer you think is correct.

(i) On a sphere of radius r there exists a curve that has curvature less than $\frac{1}{r}$ at some point.

true _____ false _____

(ii) The two principal vectors at a surface point are always orthogonal to each other.

true _____ false _____

(iii) Two surface patches $\sigma_1, \sigma_2: U \rightarrow \mathbb{R}^3$ with the same first fundamental form must have the same area.

true _____ false _____

(iv) An orientable surface patch $\sigma(u, v)$ satisfies $\sigma_u \times \sigma_v \neq 0$ at every point.

true _____ false _____

(b) [4 pts] A projective transformation $L: \mathbb{P}^3 \rightarrow \mathbb{P}^3$ is represented by the matrix

$$\begin{pmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & o & p \end{pmatrix}.$$

Under what condition(s) is L an affine transformation?

(c) [4 pts] In homogeneous coordinates describe the intersection of these two lines:

$$3x - y = 1 \quad \text{and} \quad -6x + 2y = 4.$$

(d) [4 pts] The homogeneous transformation matrix

$$\begin{pmatrix} -\frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ \frac{\sqrt{3}}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

represents a

- | | |
|-------|-------------|
| _____ | translation |
| _____ | rotation |
| _____ | reflection |

(e) [6 pts] An object has its body frame initially aligned with the world frame. Then it rotates about the body y -, x -, and z -axes sequentially by the angles α, β, γ , respectively. Describe the overall transformation as a product of matrices determined by the three Euler angles. (Note that a point is represented as a column vector.)

(f) [4 pts] The plane curve $\alpha(t)$ has a simple vertex at $t = a$ if

(g) [(6 pts)] Let $\alpha(t)$ be a curve in \mathbb{R}^3 . Denote by v, κ, τ, T, N, B its speed, curvature, torsion, tangent, principal normal, and binormal, respectively. Give the Frenet formulas that describe the curve.

(h) [4 pts] The total Gaussian curvature of an ellipsoid $\frac{x^2}{4} + \frac{y^2}{9} + \frac{z^2}{16} = 1$ is _____.

2. [14 pts] *Perspective Projection*

A projection with viewpoint \mathbf{v} and viewplane vector \mathbf{n} , all in homogeneous coordinates, is characterized by the matrix $M = \mathbf{v}\mathbf{n}^T - (\mathbf{n} \cdot \mathbf{v})I_4$, where I_4 is the 4×4 identity matrix. Consider the perspective projection from the viewpoint $(1, 1, 2)$ onto the viewplane $z - y = 3$, all in Cartesian coordinates.

(a) [6 pts] Compute the matrix M describing the above projection.

(b) [8 pts] Find the vanishing points in the three principal directions.

3. [16 pts] *Quaternions and Rotations*

Two rotations are carried out one after another. The first rotation is about the vector $(1, 1, 0)$ through an angle of $\frac{\pi}{2}$. It transforms a point \mathbf{v} into \mathbf{v}' . The second rotation is about the vector $(0, -1, 0)$ through an angle of $\frac{3\pi}{2}$. It transforms the point \mathbf{v}' into \mathbf{v}'' .

(a) [6 pts] Give the quaternions p and q that describe the first and second rotations, respectively.

(b) [10 pts] Determine the quaternion that represents the composite rotation from \mathbf{v} to \mathbf{v}'' . What are the axis \mathbf{u} and the angle θ of the composite rotation? [Use $\text{atan2}(s, c)$ to denote the angle $\alpha \in [0, 2\pi)$ such that $\sin \alpha = s$ and $\cos \alpha = c$.]

4. [12 pts] *Space Curves*

Compute the curvature κ , torsion τ , unit tangent T , principal normal N , and binormal B for the following curve:

$$\boldsymbol{\alpha}(t) = \left(\frac{4}{5} \cos t, 1 - \sin t, -\frac{3}{5} \cos t \right).$$

5. [14 pts] *Surfaces*

Calculate the Gaussian curvature of the surface

$$\sigma(u, v) = (u + v, u - v, uv)$$

at the point $(2, 0, 1)$.